Name		Partner		Date			
Glider Mass, m:		Sonic Ranger (Sonic Ranger Calibration (Gain and Offset):				
		Gain = 172.2 m/s Offset = 1.90 m					
		Force Probe C	Force Probe Calibration (Gain and Offset):				
		(Gain = -12.54 N/V Offset = 0.0045 N				
Data for glider colliding with different object types							
Object	Initial Momentum	Final Momentum	Impulse	Momentum	Coefficient of		
	p_i	p_f	J	Change	Restitution		
	(kg m/s)	(kg m/s)	(N s = kg m/s)	$\Delta p = p_f - p_i$	ϵ		
				(kg m/s)			
Spring							
Rubber Bumper							
Clay							
Show an example of how you calculate the momentum change (and uncertainty)							
show an example of now you calculate the momentum change (and ancertainty)							
Show an example of how you compare the momentum change to the impulse using the difference							
method.							
Write a short paragraph that summarizes whether your data supports the principle that the change in							
momentum of the glider is equal to the impulse it experiences in the collision.							

Name	Partner	Date			
Write a statement comparing the coefficients of restitution for the different collision types.					
Attachments:					
☐ Graphs showing position, mome	ntum, and force versus time for the sim	ulated collision in VPython.			